

**Amendments to the Abstract:**

Please replace the abstract with the following new abstract:

In a constant velocity universal joint including a double roller type roller unit, a cylindrical surface is formed in a radially outer surface of the outer roller; a flat engagement surface which is engaged with the cylindrical surface is formed in each of the guide grooves of the outer joint member; and the cylindrical surface satisfies following two equations,  $W1 > PCR (1 - \cos\theta) / 2 + \mu_3 R3 + \mu_2 R1$ ,  $W2 > 3PCR (1 - \cos\theta) / 2 - \mu_3 R3 + \mu_2 R1$ , wherein  $W1, W2$ : a length from a center of the cylindrical surface to each of axially both end portions;  $PCR$ : a distance from an axis of the inner joint member to a center of the convex sphere of each of the leg shafts;  $\theta$ : a required maximum joint angle;  $R1, R3$ : radii of the cylindrical surface and the concave sphere, respectively; and  $\mu_2, \mu_3$ : friction coefficients between the inner roller and the outer roller, and between the convex sphere and the concave sphere, respectively.